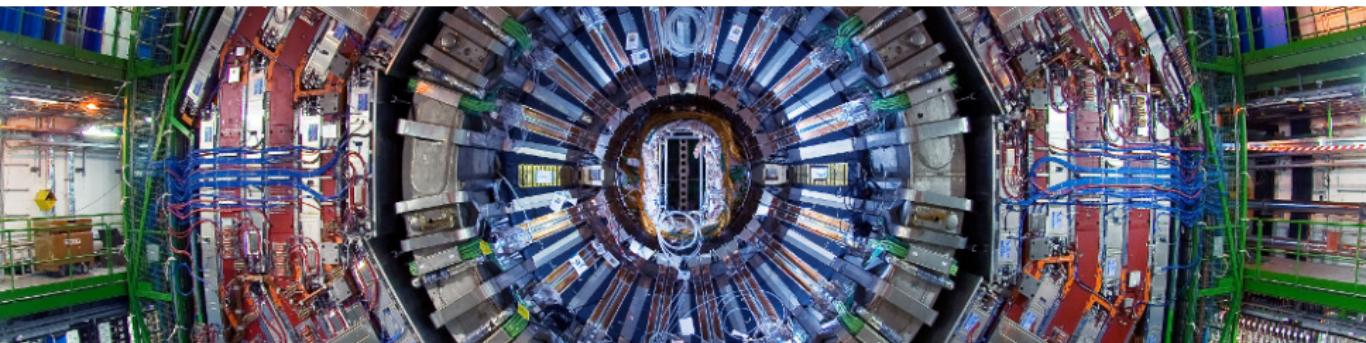


# Luminosity Measurements at the CMS Experiment.

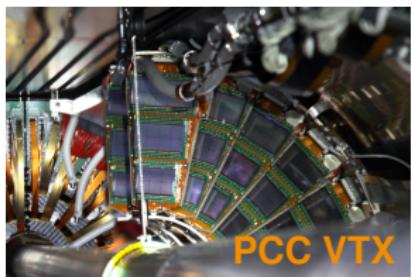
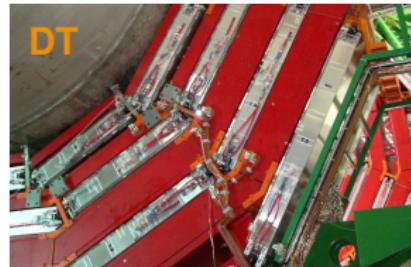
Towards reduction of the systematic uncertainty



Joscha Knolle, Andreas B. Meyer

DPG-Frühjahrstagung in Münster  
March 27–31, 2017

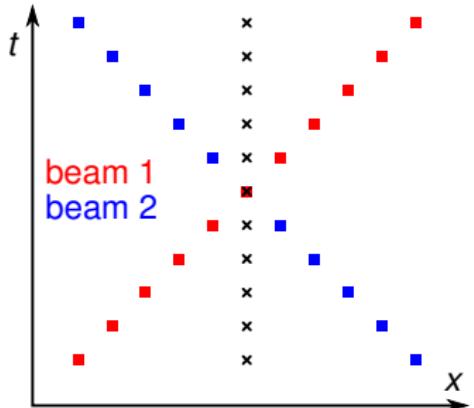
# Measuring Luminosity



$$\frac{dN}{dt} = \mathcal{L} \cdot \sigma_{\text{vis}}$$

- > luminosity: measure for number of collisions
- > measurement of luminosity:
  1. calibrate visible cross section  $\sigma_{\text{vis}}$
  2. collect event rate over whole year

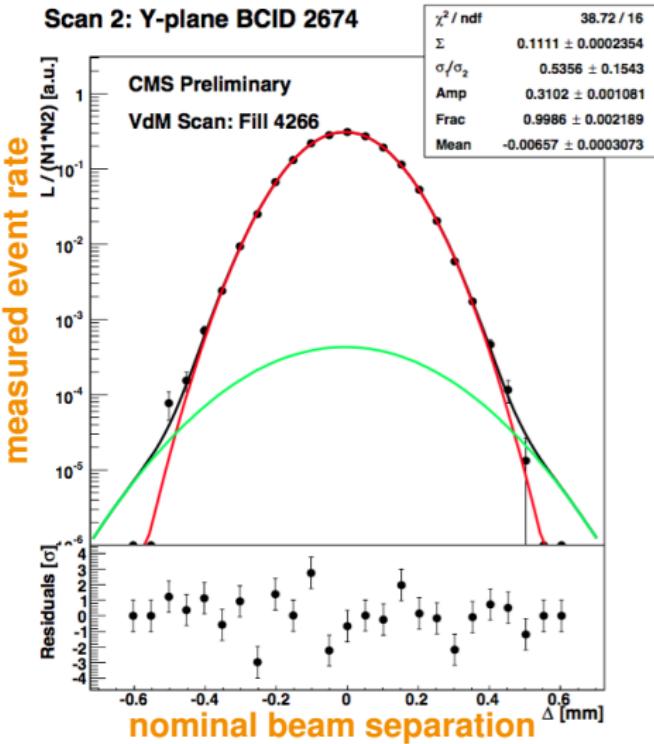
# Van der Meer Scan Method



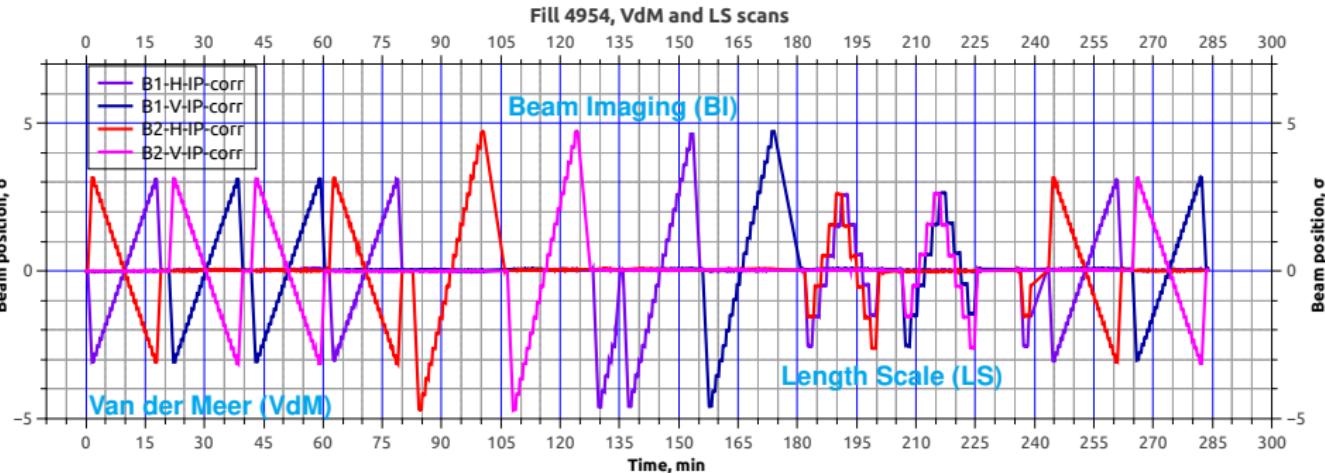
$$\Sigma_x = \frac{1}{\sqrt{2\pi}R_0} \int_{-\infty}^{+\infty} R(\Delta x) d(\Delta x)$$

$$\sigma_{\text{vis}} = \frac{2\pi}{N_1 N_2 f} \Sigma_x \Sigma_y R_0$$

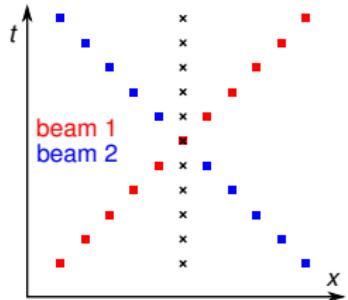
- > assume factorizable beam shape
- > take nominal beam positions



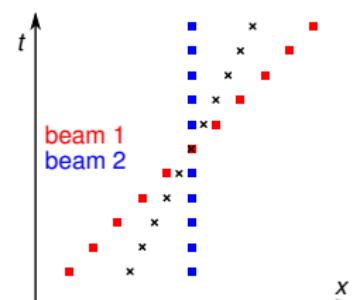
# VdM Scan Campaign in 2016



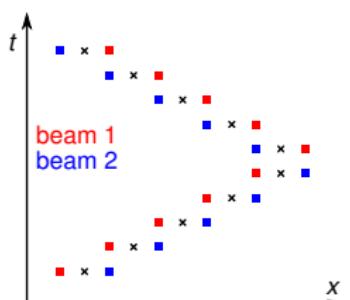
Van der Meer scans



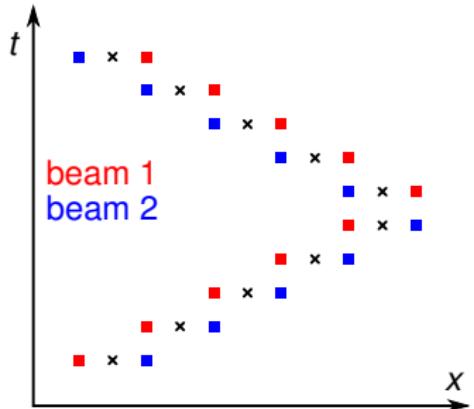
Beam Imaging scans



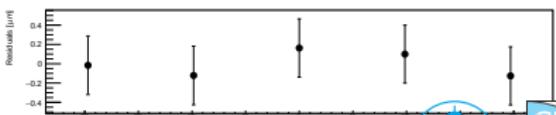
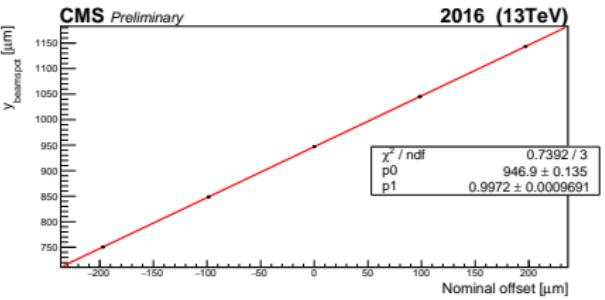
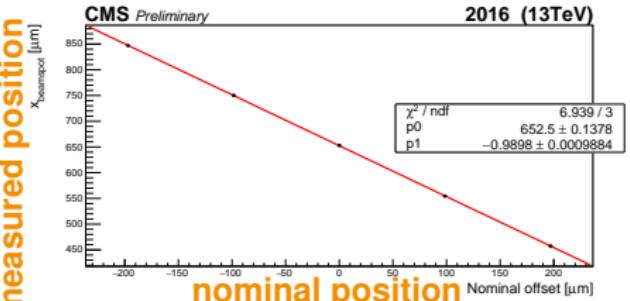
Length Scale scans



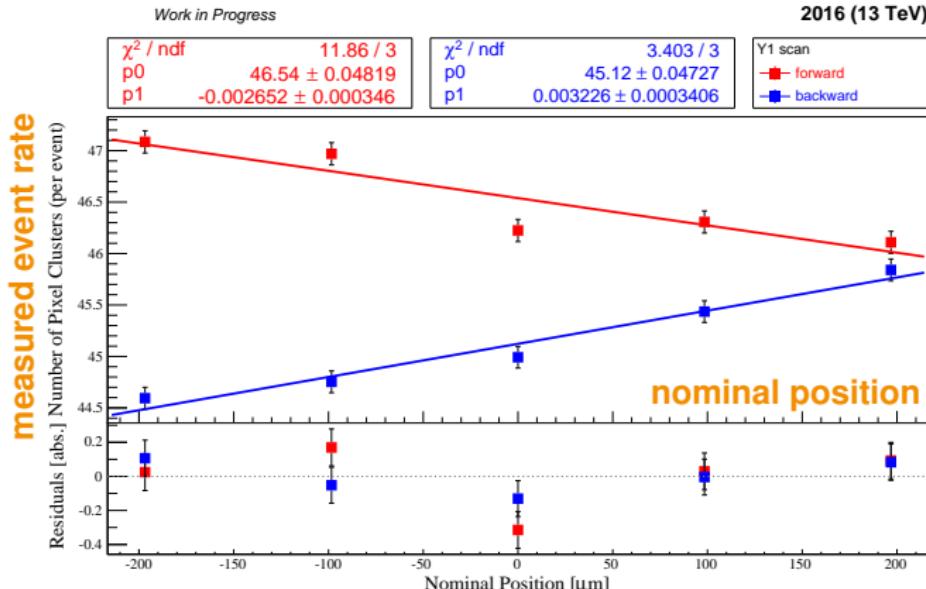
# Average Length Scale Corrections



- measure vertex position as function of nominal position
- obtain correction:
  - 1.1 % horizontally
  - 0.5 % vertically
  - ±0.8 % uncertainty



# Per-Beam Length Scale Corrections



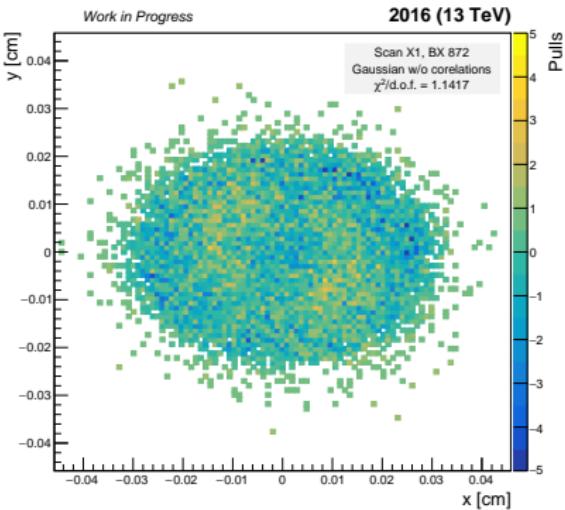
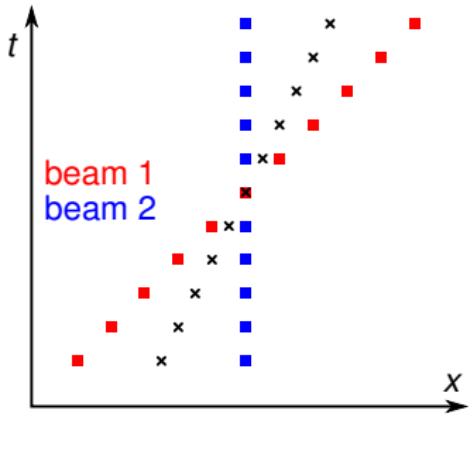
> beam 1:

–0.8 % horizontally  
–1.0 % vertically

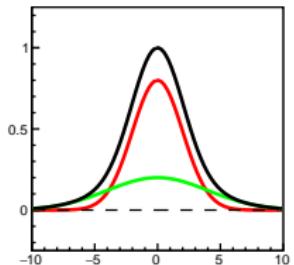
> beam 2:

–1.3 % horizontally  
–0.1 % vertically

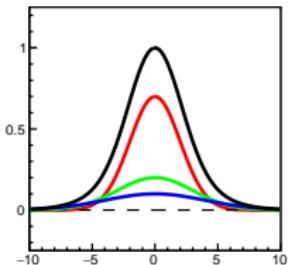
# Beam Shape Modelling



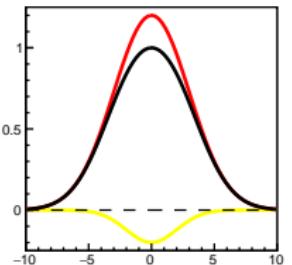
Double Gaussian



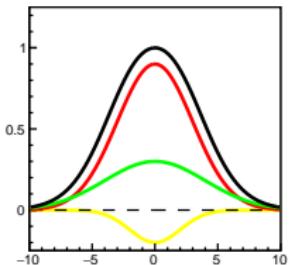
Triple Gaussian



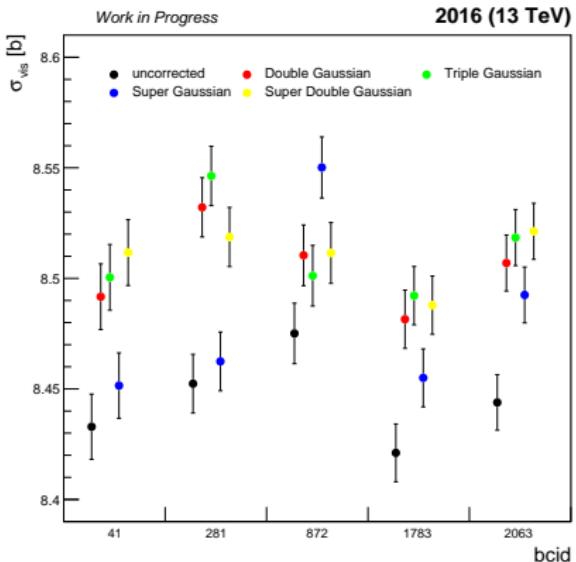
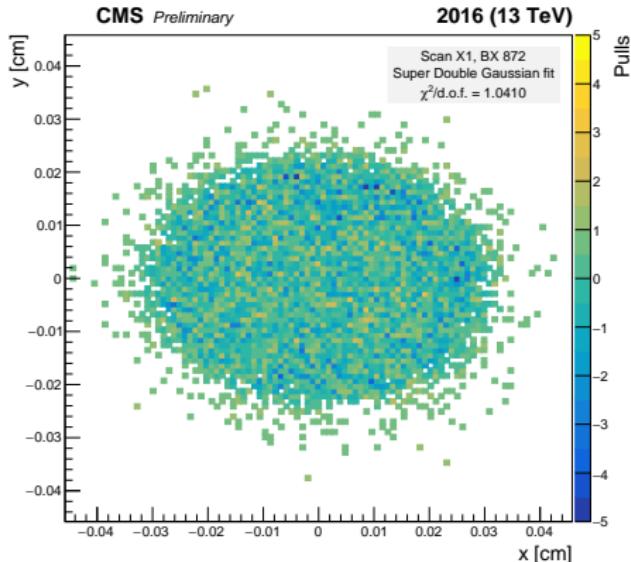
Super Gaussian



Super Double Gaussian



# XY Correlation Corrections



> best fit: Super Double Gaussian model

> correction: +0.8 %  
> uncertainty:  $\pm 0.9 \%$

# Conclusions: Uncertainty of Measured Luminosity

| Systematic                        | 2015 (CMS-PAS-LUM-15-001) |                 | 2016 (CMS-PAS-LUM-17-001) |                 |
|-----------------------------------|---------------------------|-----------------|---------------------------|-----------------|
|                                   | Correction [%]            | Uncertainty [%] | Correction [%]            | Uncertainty [%] |
| <b>INTEGRATION</b>                |                           |                 |                           |                 |
| <b>Internal stability</b>         |                           |                 | –                         | 0.5             |
| <b>Cross detector stability</b>   | –                         | 1.0             | –                         | 1.5             |
| <b>Linearity</b>                  |                           |                 | –                         | 0.6             |
| <b>Dynamic inefficiency</b>       | –                         | 0.4             | 0 – 1                     | 0.3             |
| <b>Type 1 corrections</b>         | 7 – 9                     | 0.6             | 7 – 12                    | 0.7             |
| <b>Type 2 corrections</b>         | 0 – 4                     | 0.7             | 0 – 4                     | 0.5             |
| <b>CMS deadtime</b>               | –                         | 0.5             | –                         | 0.5             |
| <b>NORMALIZATION</b>              |                           |                 |                           |                 |
| <b>XY correlations</b>            | 1.1                       | 1.5             | 0.8                       | 0.9             |
| <b>Beam current calibration</b>   | –                         | 0.3             | –                         | 0.3             |
| <b>Ghosts and satellites</b>      | –                         | 0.2             | –                         | 0.4             |
| <b>Length scale</b>               | -0.5                      | 0.5             | -1.6                      | 0.8             |
| <b>Orbit drift</b>                | –                         | 0.4             | –                         | 0.4             |
| <b>Beam-beam deflection</b>       | 1.8                       | 0.4             | 1.5                       | 0.4             |
| <b>Dynamic-<math>\beta</math></b> | –                         | 0.5             | –                         | 0.5             |
| <b>TOTAL</b>                      |                           | 2.3             |                           | 2.5             |

# Thank you for your attention.

